

Probabilistic modelling for NLP powered by deep learning

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Outline

- 1 Deep generative models
- 2 Variational inference
- 3 Variational auto-encoder

Problems

Supervised problems

*“learn a distribution over **observed** data”*

- sentences in natural language
- images, ...

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Unsupervised problems

*“learn a distribution over **observed** and **unobserved** data”*

- sentences in natural language + parse trees
- images + bounding boxes, ...

Supervised problems

We have data $x^{(1)}, \dots, x^{(N)}$ e.g.

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- with **known** probability (mass/density) function e.g.

$$\underbrace{X \sim \text{Cat}(\pi_1, \dots, \pi_K)}_{\text{e.g. nationality}}$$

or

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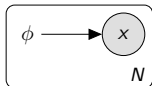
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estimate parameters that assign maximum likelihood to observations

Multiple problems, same language



(Conditional) Density estimation

	Side information (ϕ)	Observation (x)
Parsing	a sentence	parse tree
Translation	a sentence in French	translation in English
Captioning	an image	caption in English
Entailment	a text and hypothesis	entailment relation

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and proceed to **estimate parameters** θ of the NNs

NN as efficient parametrisation

From the statistical point of view NNs do not generate data

- they parametrise distributions that *by assumption* govern data
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Prediction is done by a decision rule outside the statistical model

- e.g. beam search

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quantifies the fitness of our model to data

MLE via gradient-based optimisation

If assessing the log-likelihood is **differentiable** and assessing it is **tractable**, then backpropagation can give us the gradient

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and we can update θ in the direction

$$\gamma \nabla_{\theta} \mathcal{L}(\theta | x^{(1:N)})$$

to attain a local optimum of the likelihood function

Stochastic optimisation

We can also use a gradient estimate

$$\nabla_{\theta} \mathcal{L}(\theta | x^{(1:N)}) = \nabla_{\theta} \underbrace{\mathbb{E}_{S \sim \mathcal{U}(1..N)} \left[N \log p(x^{(S)} | \theta) \right]}_{\mathcal{L}(\theta | x^{(1:N)})}$$

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and take steps in the direction

$$\gamma \frac{N}{M} \nabla_{\theta} \mathcal{L}(\theta | x^{(s_1:s_M)})$$

where $x^{(s_1)}, \dots, x^{(s_M)}$ is a random mini-batch of size M

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- chain rule of derivatives: “give me a tractable forward pass and I will give you **gradients**”

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Stochastic optimisation powered by backprop

- general purpose gradient-based optimisers

Tractability is central

- Likelihood gives us a differentiable objective to optimise for
- but we need to stick with **tractable** likelihood functions

When do we have intractable likelihood?

Unsupervised problems contain unobserved random variables

$$p_{\theta}(x, z) = \overbrace{p(z)}^{\text{latent variable model}} \underbrace{p_{\theta}(x|z)}_{\text{observation model}}$$

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$$p_{\theta}(x, z) = \overbrace{p(z)}^{\text{latent variable model}} \underbrace{p_{\theta}(x|z)}_{\text{observation model}}$$

thus assessing the marginal likelihood requires **marginalisation of latent variables**

$$p_{\theta}(x) = \int p_{\theta}(x, z) dz = \int p(z)p_{\theta}(x|z) dz$$

Examples of latent variable models

Discrete latent variable, continuous observation

- too many forward passes

$$p_{\theta}(x) = \sum_{c=1}^K \text{Cat}(c|\pi_1, \dots, \pi_K) \underbrace{\mathcal{N}(x|\mu_{\theta}(c), \sigma_{\theta}(c)^2)}_{\text{forward pass}}$$

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Continuous latent variable, discrete observation

- infinitely many forward passes

$$p_{\theta}(x) = \int \mathcal{N}(z|0, I) \underbrace{\text{Cat}(x|\pi_{\theta}(z))}_{\text{forward pass}} dz$$

Deep generative models

Joint distribution with **deep observation model**

$$p_{\theta}(x, z) = \underbrace{p(z)}_{\text{prior}} \underbrace{p_{\theta}(x|z)}_{\text{likelihood}}$$

mapping from latent variable z to $p(x|z)$ is a NN with parameters θ

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Marginal likelihood (or evidence)

$$p_{\theta}(x) = \int p_{\theta}(x, z) dz = \int p(z)p_{\theta}(x|z) dz$$

intractable in general

Gradient

Exact gradient is intractable

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Can we get an estimate?

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MC estimate of gradient requires sampling from posterior

$$p_{\theta}(z|x) = \frac{p(z)p_{\theta}(x|z)}{p_{\theta}(x)}$$

unavailable due to the intractability of the marginal

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We need **approximate inference** techniques!

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The Basic Problem

The marginal likelihood

$$p(x) = \int p(x, z) dz$$

is generally **intractable**, which prevents us from computing quantities that depend on the posterior $p(z|x)$

- e.g. gradients in MLE
- e.g. predictive distribution in Bayesian modelling

Strategy

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- approximate it by an auxiliary distribution $q(z|x)$ that is computable
- choose $q(z|x)$ as close as possible to $p(z|x)$ to obtain a faithful approximation

Evidence lowerbound

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 &= \mathbb{E}_{q(z|x)} [\log p(x, Z)] - \mathbb{E}_{q(z|x)} [\log q(Z)]
 \end{aligned}$$

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 &= \mathbb{E}_{q(z|x)} [\log p(x, Z)] - \mathbb{E}_{q(z|x)} [\log q(Z)] \\
 &= \mathbb{E}_{q(z|x)} [\log p(x, Z)] + \mathbb{H}(q(z|x))
 \end{aligned}$$

An approximate posterior

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 \end{aligned}$$

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 &= \mathbb{E}_{q(z|x)} \left[\log \frac{p(Z|x)}{q(Z|x)} \right] + \underbrace{\log p(x)}_{\text{constant}} \\
 &= - \underbrace{\mathbb{E}_{q(z|x)} \left[\log \frac{q(Z|x)}{p(Z|x)} \right]}_{\text{KL}(q(z|x)||p(z|x))} + \log p(x)
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 \end{aligned}$$

We have derived a lower bound on the log-evidence whose gap is exactly $\text{KL}(q(z|x) || p(z|x))$.

Variational Inference

Objective

$$\max_{q(z|x)} \mathbb{E} [\log p(x, Z)] + \mathbb{H}(q(z|x))$$

- The ELBO is a lower bound on $\log p(x)$

Mean field assumption

Suppose we have N latent variables

- assume the posterior factorises as N independent terms
- each with an independent set of parameters

$$q(z_1, \dots, z_N) = \underbrace{\prod_{i=1}^N q_{\lambda_i}(z_i)}_{\text{mean field}}$$

Amortised variational inference

Amortise the cost of inference using NNs

$$q(z_1, \dots, z_N | x_1, \dots, x_N) = \prod_{i=1}^N q_{\lambda}(z_i | x_i)$$

with a shared set of parameters

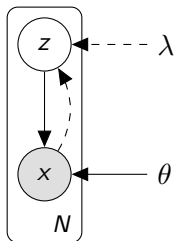
- e.g. $Z|x \sim \mathcal{N}(\underbrace{\mu_{\lambda}(x), \sigma_{\lambda}(x)^2}_{\text{inference network}})$

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Variational auto-encoder

Generative model with NN likelihood



- complex (non-linear) observation model $p_{\theta}(x|z)$
- complex (non-linear) mapping from data to latent variables $q_{\lambda}(z|x)$

Jointly optimise generative model $p_{\theta}(x|z)$ and inference model $q_{\lambda}(z|x)$ under the same objective (ELBO)

$$\log p_{\theta}(x) \geq \overbrace{\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x, Z)] + \mathbb{H}(q_{\lambda}(z|x))}^{\text{ELBO}}$$

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Parameter estimation

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Parameter estimation

$$\arg \max_{\theta, \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|Z)] - \text{KL}(q_{\lambda}(z|x) \parallel p(z))$$

- assume $\text{KL}(q_{\lambda}(z|x) \parallel p(z))$ analytical
true for exponential families

$$\begin{aligned}\log p_{\theta}(x) &\geq \overbrace{\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x, Z)] + \mathbb{H}(q_{\lambda}(z|x))}^{\text{ELBO}} \\ &= \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|Z) + \log p(Z)] + \mathbb{H}(q_{\lambda}(z|x)) \\ &= \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|Z)] - \text{KL}(q_{\lambda}(z|x) || p(z))\end{aligned}$$

Parameter estimation

$$\arg \max_{\theta, \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|Z)] - \text{KL}(q_{\lambda}(z|x) || p(z))$$

- assume $\text{KL}(q_{\lambda}(z|x) || p(z))$ analytical
true for exponential families
- approximate $\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)]$ by sampling
true because we design $q_{\lambda}(z|x)$ to be simple

Generative Network Gradient

$$\frac{\partial}{\partial \theta} \left(\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] - \overbrace{\text{KL}(q_{\lambda}(z|x) || p(z))}^{\text{constant wrt } \theta} \right)$$

Generative Network Gradient

$$\begin{aligned} & \frac{\partial}{\partial \theta} \left(\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] - \overbrace{\text{KL}(q_{\lambda}(z|x) || p(z))}^{\text{constant wrt } \theta} \right) \\ &= \underbrace{\mathbb{E}_{q_{\lambda}(z|x)} \left[\frac{\partial}{\partial \theta} \log p_{\theta}(x|z) \right]}_{\text{expected gradient :)}} \end{aligned}$$

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Note: $q_\lambda(z|x)$ does not depend on θ .

Inference Network Gradient

$$\frac{\partial}{\partial \lambda} \left(\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] - \overbrace{\text{KL}(q_{\lambda}(z|x) || p(z))}^{\text{analytical}} \right)$$

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The first term again requires approximation by sampling,
 but there is a problem

Inference Network Gradient

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)]$$

Inference Network Gradient

$$\begin{aligned} & \frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] \\ &= \frac{\partial}{\partial \lambda} \int q_{\lambda}(z|x) \log p_{\theta}(x|z) dz \end{aligned}$$

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- MC estimator is non-differentiable: cannot sample first

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- MC estimator is non-differentiable: cannot sample first
- Differentiating the expression does not yield an expectation: cannot approximate via MC

Score function estimator

We can again use the log identity for derivatives

$$\begin{aligned}
 & \frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] \\
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Score function estimator: high variance

We can now build an MC estimator

$$\begin{aligned} & \frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] \\ &= \mathbb{E}_{q_{\lambda}(z|x)} \left[\log p_{\theta}(x|z) \frac{\partial}{\partial \lambda} \log q_{\lambda}(z|x) \right] \end{aligned}$$

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- magnitude of $\log p_\theta(x|z)$ varies widely

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but

- magnitude of $\log p_\theta(x|z)$ varies widely
- model likelihood does not contribute to direction of gradient
- too much variance to be useful

When variance is high we can

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- use variance reduction techniques (e.g. baselines and control variates)
excellent idea, but not just yet
- stare at this $\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)]$
until we find a way to rewrite the expectation in terms of a density that **does not depend on λ**

Reparametrisation

Find a transformation $h : z \mapsto \epsilon$ that expresses z through a random variable ϵ such that $q(\epsilon)$ does not depend on λ

(Kingma and Welling, 2013; Rezende et al., 2014; Titsias and Lázaro-Gredilla, 2014)

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Invertibility implies

- $h(z, \lambda) = \epsilon$
- $h^{-1}(\epsilon, \lambda) = z$

(Kingma and Welling, 2013; Rezende et al., 2014; Titsias and Lázaro-Gredilla, 2014)

Gaussian Transformation

If $Z \sim \mathcal{N}(\mu_\lambda(x), \sigma_\lambda(x)^2)$ then

$$h(z, \lambda) = \frac{z - \mu_\lambda(x)}{\sigma_\lambda(x)} = \epsilon \sim \mathcal{N}(0, 1)$$

$$h^{-1}(\epsilon, \lambda) = \mu_\lambda(x) + \sigma_\lambda(x) \odot \epsilon \quad \epsilon \sim \mathcal{N}(0, 1)$$

$$= \frac{\partial}{\partial \lambda} \int q_{\lambda}(z|x) \log p_{\theta}(x|z) dz$$

$$\begin{aligned} &= \frac{\partial}{\partial \lambda} \int q_{\lambda}(z|x) \log p_{\theta}(x|z) dz \\ &= \frac{\partial}{\partial \lambda} \int q(\epsilon) \log p_{\theta}(x | \overbrace{h^{-1}(\epsilon, \lambda)}^{=z}) d\epsilon \end{aligned}$$

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&= \underbrace{\mathbb{E}_{q(\epsilon)} \left[\frac{\partial}{\partial \lambda} \log p_{\theta}(x | h^{-1}(\epsilon, \lambda)) \right]}_{\text{expected gradient :D}} d\epsilon
\end{aligned}$$

Reparametrised gradient estimate

$$= \underbrace{\mathbb{E}_{q(\epsilon)} \left[\frac{\partial}{\partial \lambda} \log p_{\theta}(x|h^{-1}(\epsilon, \lambda)) \right]}_{\text{expected gradient :D}} d\epsilon$$

Reparametrised gradient estimate

$$\begin{aligned} &= \underbrace{\mathbb{E}_{q(\epsilon)} \left[\frac{\partial}{\partial \lambda} \log p_{\theta}(x|h^{-1}(\epsilon, \lambda)) \right]}_{\text{expected gradient :D}} d\epsilon \\ &= \mathbb{E}_{q(\epsilon)} \left[\underbrace{\frac{\partial}{\partial z} \log p_{\theta}(x| \overset{=z}{h^{-1}(\epsilon, \lambda)})}_{\text{chain rule}} \times \frac{\partial}{\partial \lambda} h^{-1}(\epsilon, \lambda) \right] \end{aligned}$$

Reparametrised gradient estimate

$$\begin{aligned} &= \underbrace{\mathbb{E}_{q(\epsilon)} \left[\frac{\partial}{\partial \lambda} \log p_{\theta}(x | h^{-1}(\epsilon, \lambda)) \right]}_{\text{expected gradient :D}} d\epsilon \\ &= \mathbb{E}_{q(\epsilon)} \left[\underbrace{\frac{\partial}{\partial z} \log p_{\theta}(x | \overbrace{h^{-1}(\epsilon, \lambda)}^{=z})}_{\text{chain rule}} \times \frac{\partial}{\partial \lambda} h^{-1}(\epsilon, \lambda) \right] \\ &\stackrel{\text{MC}}{\approx} \frac{1}{K} \sum_{k=1}^K \underbrace{\frac{\partial}{\partial z} \log p_{\theta}(x | \overbrace{h^{-1}(\epsilon^{(k)}, \lambda)}^{=z})}_{\text{backprop's job}} \times \frac{\partial}{\partial \lambda} h^{-1}(\epsilon^{(k)}, \lambda) \end{aligned}$$

$$\epsilon^{(k)} \sim q(\epsilon)$$

Note that both models contribute with gradients

Gaussian KL

ELBO

$$\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] - \text{KL}(q_{\lambda}(z|x) || p(z))$$

Gaussian KL

ELBO

$$\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] - \text{KL}(q_{\lambda}(z|x) \parallel p(z))$$

Analytical computation of $-\text{KL}(q_{\lambda}(z|x) \parallel p(z))$:

$$\frac{1}{2} \sum_{i=1}^d (1 + \log(\sigma_i^2) - \mu_i^2 - \sigma_i^2)$$

Gaussian KL

ELBO

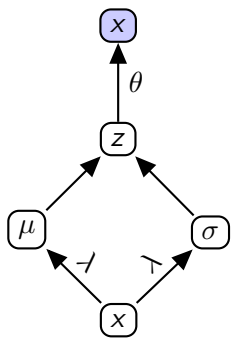
$$\mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] - \text{KL}(q_{\lambda}(z|x) || p(z))$$

Analytical computation of $-\text{KL}(q_{\lambda}(z|x) || p(z))$:

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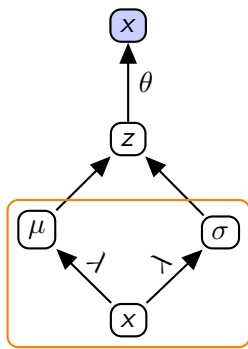
Thus backprop will compute $-\frac{\partial}{\partial \lambda} \text{KL}(q_{\lambda}(z|x) || p(z))$ for us

Computation Graph



Computation Graph

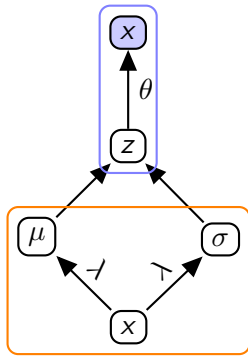
inference model



Computation Graph

generative model

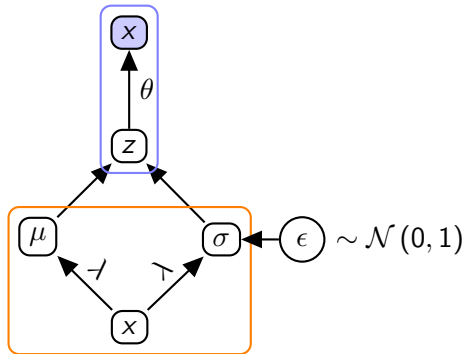
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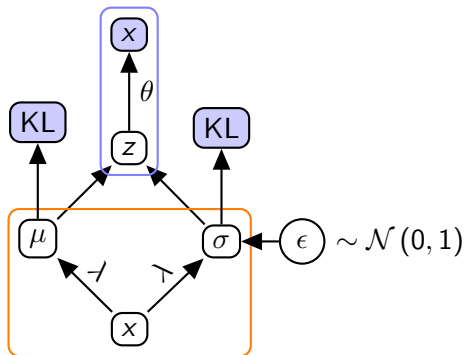
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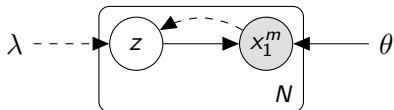
Computation Graph

generative model

inference model



Example



Generative model

- $Z \sim \mathcal{N}(0, I)$
- $X_i | z, x_{<i} \sim \text{Cat}(f_\theta(z, x_{<i}))$

Inference model

- $Z \sim \mathcal{N}(\mu_\lambda(x_1^m), \sigma_\lambda(x_1^m)^2)$

VAEs – Summary

Advantages

- Backprop training
- Easy to implement
- Posterior inference possible
- One objective for both NNs

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- Backprop training
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- Posterior inference possible
- One objective for both NNs

Drawbacks

- Discrete latent variables are difficult
- Optimisation may be difficult with several latent variables
- Location-scale families only
but see Ruiz et al. (2016) and Kucukelbir et al. (2017)

Summary

Deep learning in NLP

- task-driven feature extraction
- models with more realistic assumptions

Probabilistic modelling

- better (or at least more explicit) statistical assumptions
- compact models
- semi-supervised learning

Literature I

- Dzmitry Bahdanau, Kyunghyun Cho, and Yoshua Bengio. Neural machine translation by jointly learning to align and translate. 2014. URL <http://arxiv.org/abs/1409.0473>.
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